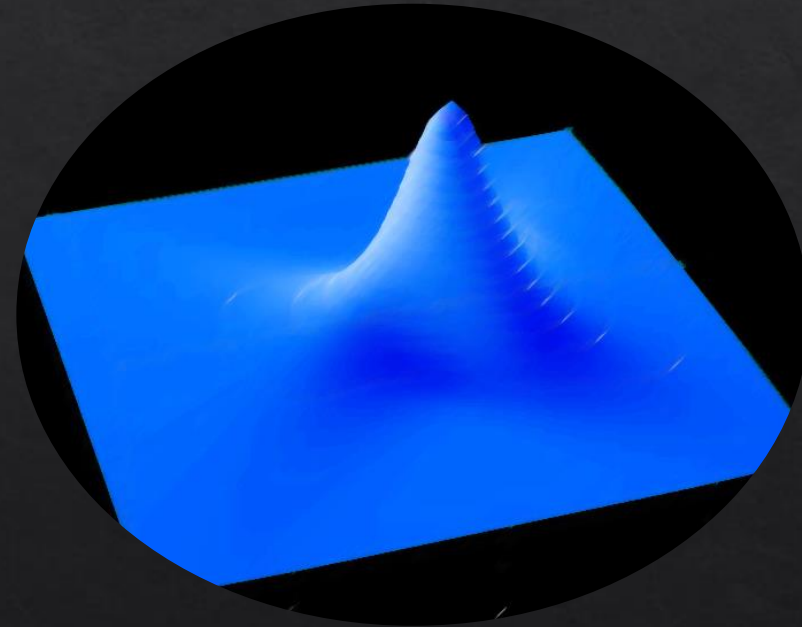
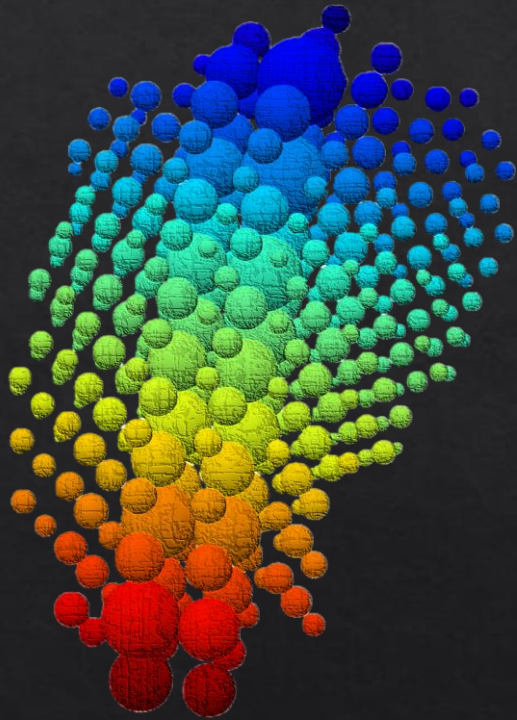


# Windchime, Heavy DM Candidates, and QFT in Curved STs

*Bahaa Elshimy*



# Overview

- ◇ Experimental Work: *Gravitational Direct Detection of Dark Matter*
- ◇ Phenomenology Work: *Heavy Dark Matter Candidates for Direct Detection Techniques*
- ◇ Theory Work: *Evolution of Free Scalar Field in Curved Spacetimes*

# Overview

- ◇ Experimental Work: *Gravitational Direct Detection of Dark Matter*
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- ◇ Theory Work: *Evolution of Free Scalar Field in Curved Spacetimes w/ Dr. Daniel Carney*

# Background

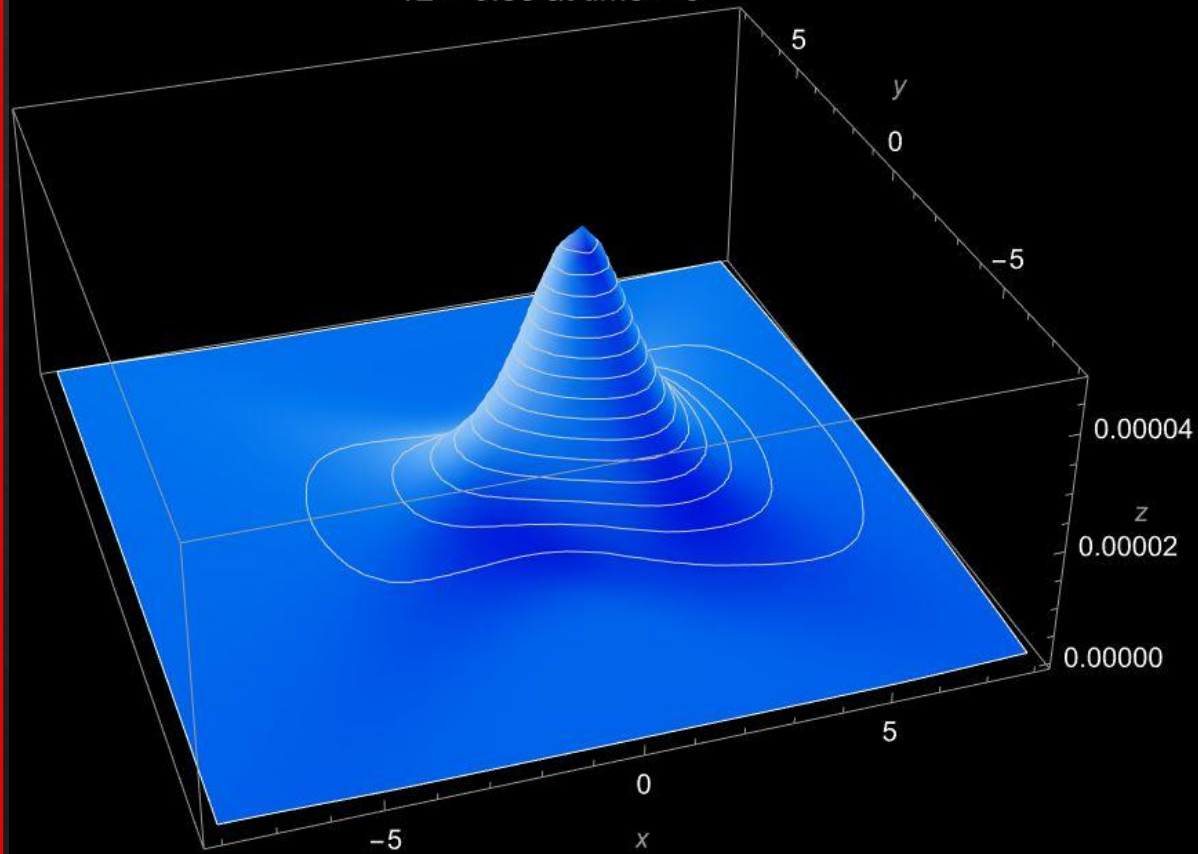
- Standard Approach: Attempt to construct a relativistic quantum theory → QFT with a Flat Background
  - Particles arise naturally as an interpretation of the nonzero components of the Fock space states in the n-fold tensor product space  $\otimes_s^n \mathcal{H}$
  - In other words, they are irreducible representations of the associated symmetry group (Poincare)
- Drawback: Relies on the unitary equivalence of the field theory regardless of choice of Hilbert Space
- In curved STs, the machinery can still work, but choice of basis is no longer clear and no longer unique
- Remedy: Reformulate the theory using a symplectic structure and an associated vector space – basically a phase space representation with a symplectic product and a Poisson Bracket

# Goal of the Analysis

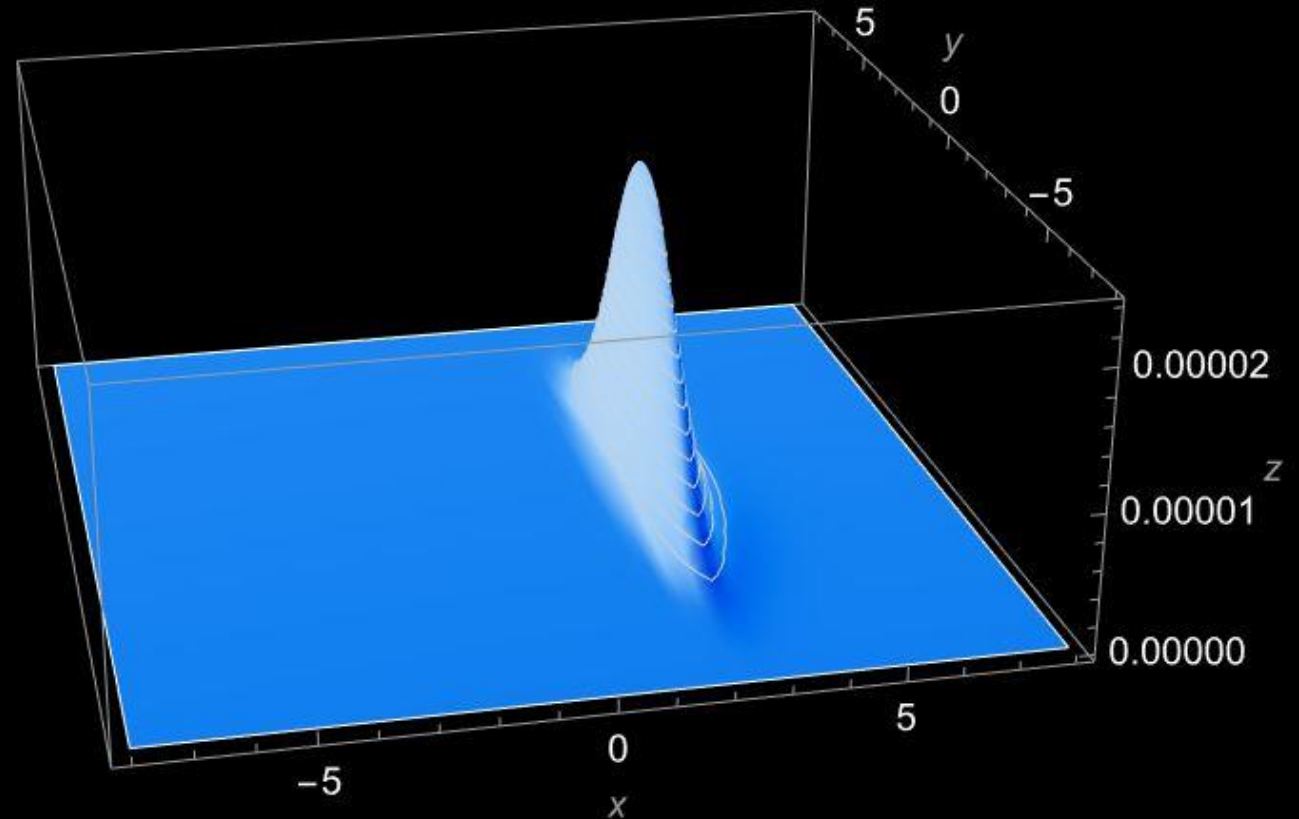
- Get the energy spectrum of the free particles with different spacetime geometries
  - Analyze what this energy depends on in different regions
- Derive the asymptotic behavior of the scalar fields
  - Determine whether a detector can use information gathered about the evolved state to infer elements of the background geometry via certain behavior observed
- Started with Curvilinear Coordinates, Boosted Frames, & Rindler Coordinates
- Concluded with Static Patch of deSitter Space

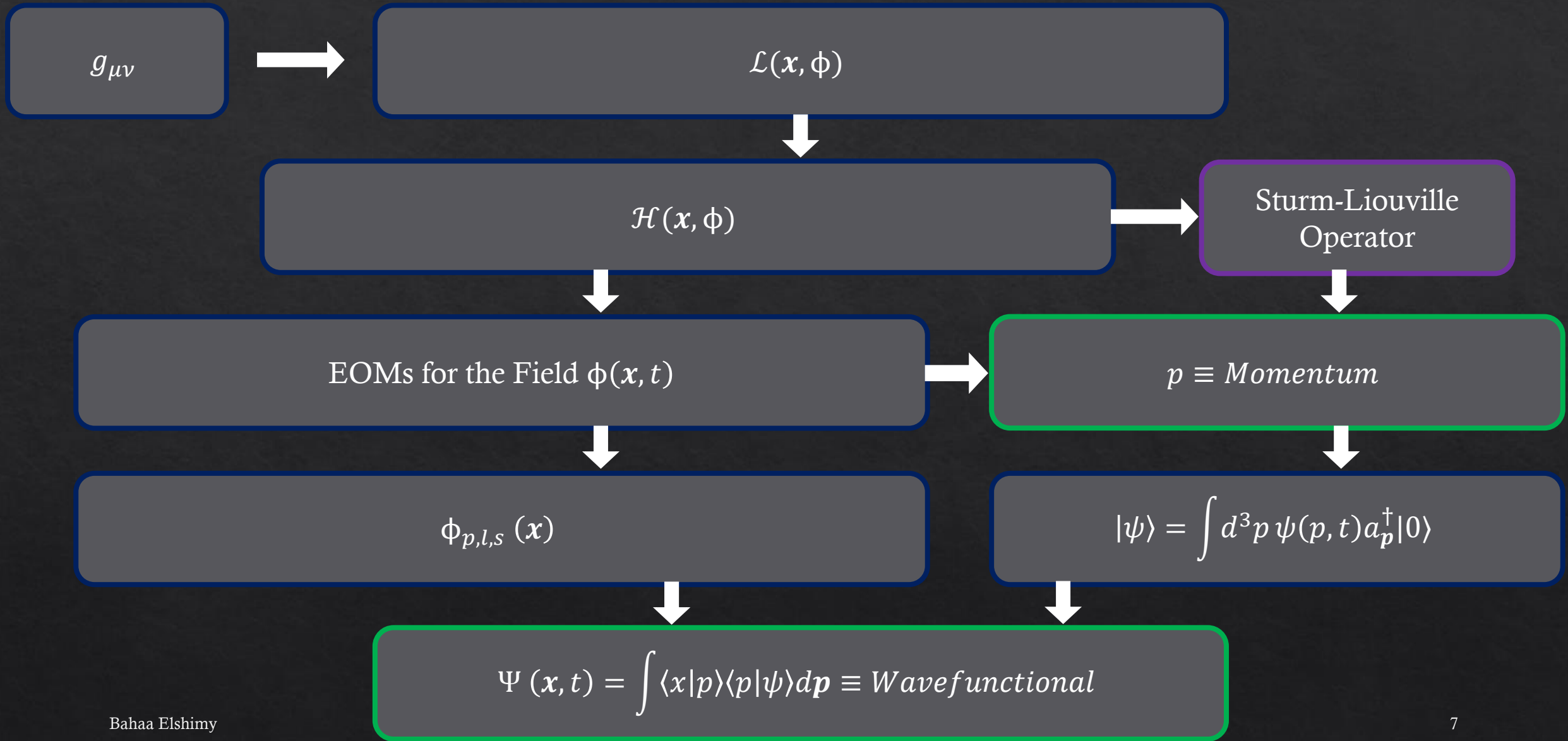
# WF in Boosted Frame

$v_2 = 0.85$  at time = 0



$v_2 = 0.99$  at time = 5





# Case 0: Flat Space Spherical Coordinates

$$\mathcal{L}(\mathbf{x}, \phi) = -\frac{1}{2} r^2 \sin \theta (-(\partial_t \phi)^2 + (\partial_r \phi)^2 + m^2 \phi^2) - \frac{1}{2} \left( \sin \theta (\partial_\theta \phi)^2 + \frac{1}{\sin \theta} (\partial_\varphi \phi)^2 \right)$$

$$\mathcal{H}(\mathbf{x}, \phi) = \frac{1}{2} \left[ \frac{\pi^2}{r^2 \sin \theta} + r^2 \sin \theta ((\partial_r \phi)^2 + m^2 \phi^2) + \sin \theta (\partial_\theta \phi)^2 + \frac{1}{\sin \theta} (\partial_\varphi \phi)^2 \right]$$

$$\hat{D} = \partial_r (r^2 \partial_r) - \hat{L}^2 - r^2 m^2$$

$$-\partial_t^2 \phi + \frac{1}{r^2} \partial_r (r^2 \partial_r \phi) + \frac{1}{r^2 \sin \theta} \partial_\theta (\sin \theta \partial_\theta \phi) + \frac{1}{r^2 \sin^2 \theta} \partial_\varphi^2 \phi - m^2 \phi = 0$$

$$p^2 = \omega_p^2 - m^2$$

$$\phi_{p,l,s}(\mathbf{x}) = R(r) Y_l^s(\theta, \varphi) = A e^{is\varphi} j_{\bar{k}_l}(pr) P_{\bar{k}_l}^s(\cos \theta)$$

$$|\psi\rangle = \psi_0 \int d^3p e^{-i\omega_p t} a_p^\dagger |0\rangle$$

$$\Psi(r, \theta, \varphi, t) = \int dp \sum_{l,s} A e^{is\varphi} j_{\bar{k}_l}(pr) P_{\bar{k}_l}^s(\cos \theta) \psi_0 e^{-i\omega_p t}$$



# Free Scalar Field in deSitter Spacetime

$$\mathcal{L}(x, \phi) = -\frac{1}{2} \cos(H\rho) \sin^2(H\rho) \sin \theta \left[ -\cos^2(H\rho) (\partial_t \phi)^2 + (\partial_\rho \phi)^2 + H^2 \sin^{-2}(H\rho) \left( (\partial_\theta \phi)^2 + \sin^{-2} \theta (\partial_\varphi \phi)^2 \right) - m^2 \phi^2 \right]$$

$$\mathcal{H}(x, \phi) \equiv \dot{\phi} \pi - \mathcal{L} \quad \pi \equiv \frac{\partial \mathcal{L}}{\partial (\partial_t \phi)} = H^{-2} \cos^{-1}(H\rho) \sin^2(H\rho) \sin \theta \dot{\phi}$$

$$D = \partial_r (r^2 \partial_r) - \widehat{L}^2 - r^2 m^2$$

EOMs

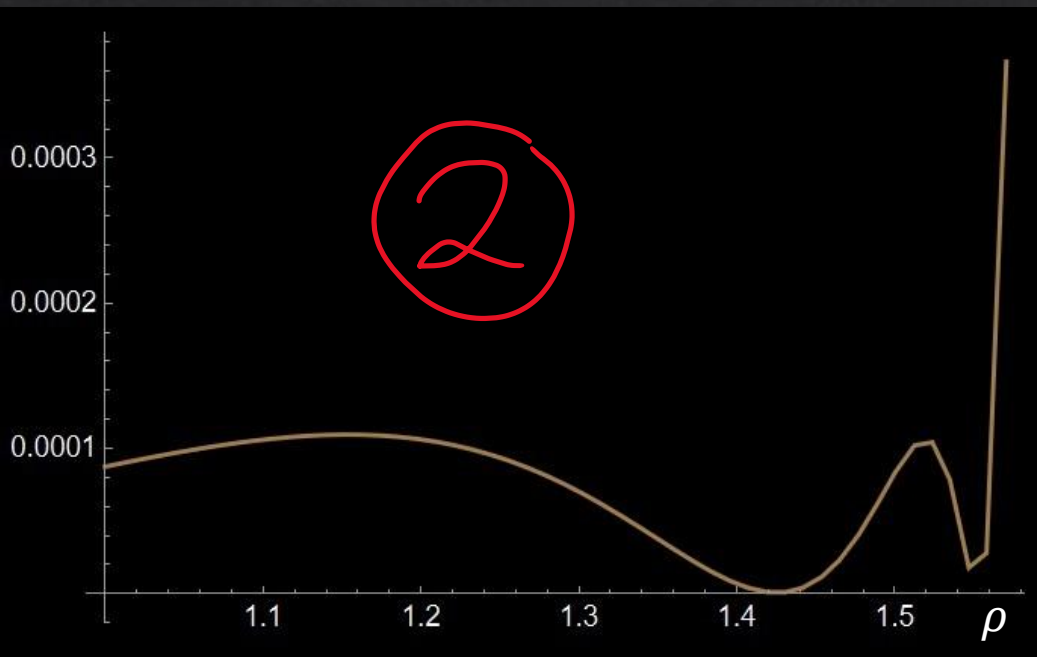
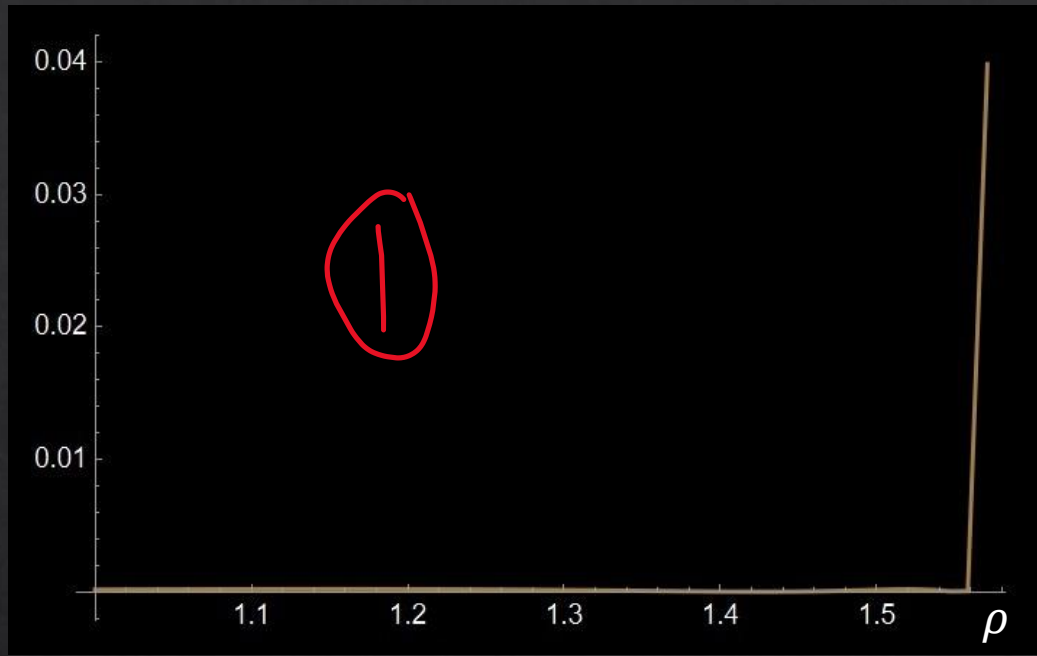
Rescaled Radial Solution  
with  $\frac{m^2}{H^2} \gg 1$

$$\phi_{p,l,s}(r, \theta, \varphi) = A_{l,s} Y_l^s(\theta, \varphi) N_{pl} \tan^l(H\rho) \cos^n(H\rho) {}_2F_1[\text{Args}\{\rho\}]$$

$|\psi\rangle$

$$p^2 = \omega_p^2 \text{ at the } \rho \rightarrow \frac{\pi}{2H} \text{ limit}$$

$$\Psi(x, t) = \int \langle x|p\rangle \langle p|\psi\rangle d\mathbf{p} = \int \phi_{\mathbf{k}}(r, \theta, \varphi, t) \psi_0 e^{-i\omega_{\mathbf{k}} t} d\mathbf{k}$$

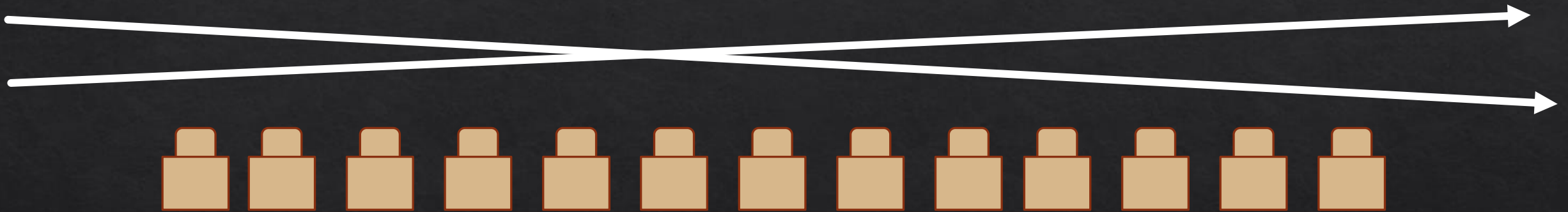


# Overview

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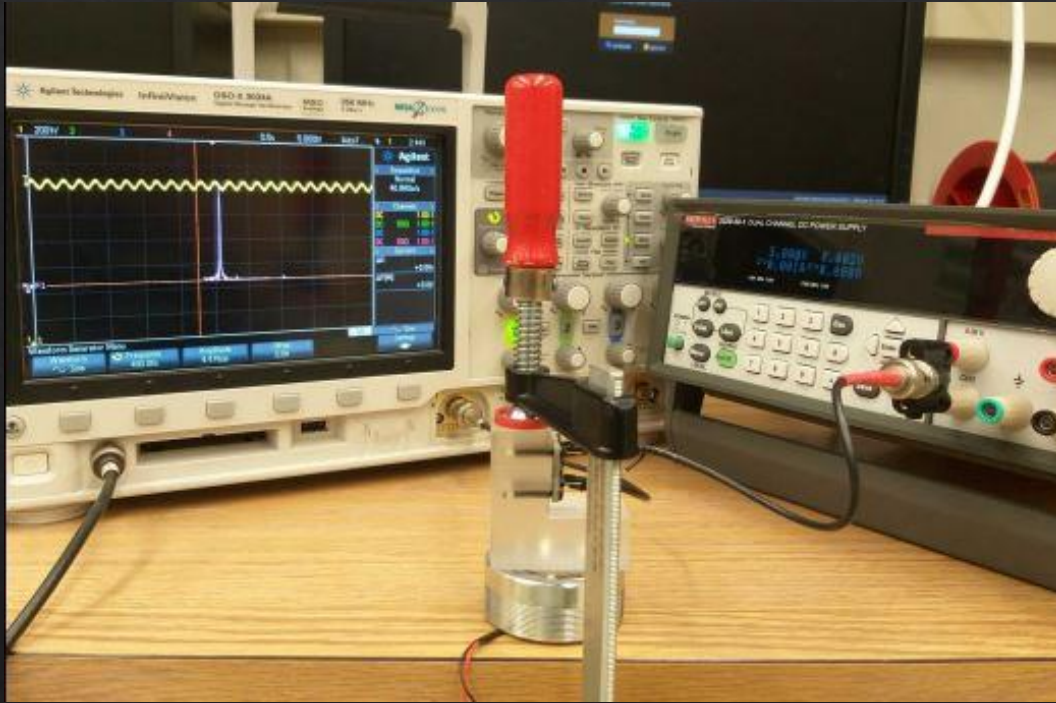
# Overview of Gravitational Detection Method

- ◇ Long-term Goal: Detect Dark Matter directly using gravitational Interactions
- ◇ Uses accelerometers jerked by their interaction with the Dark Matter



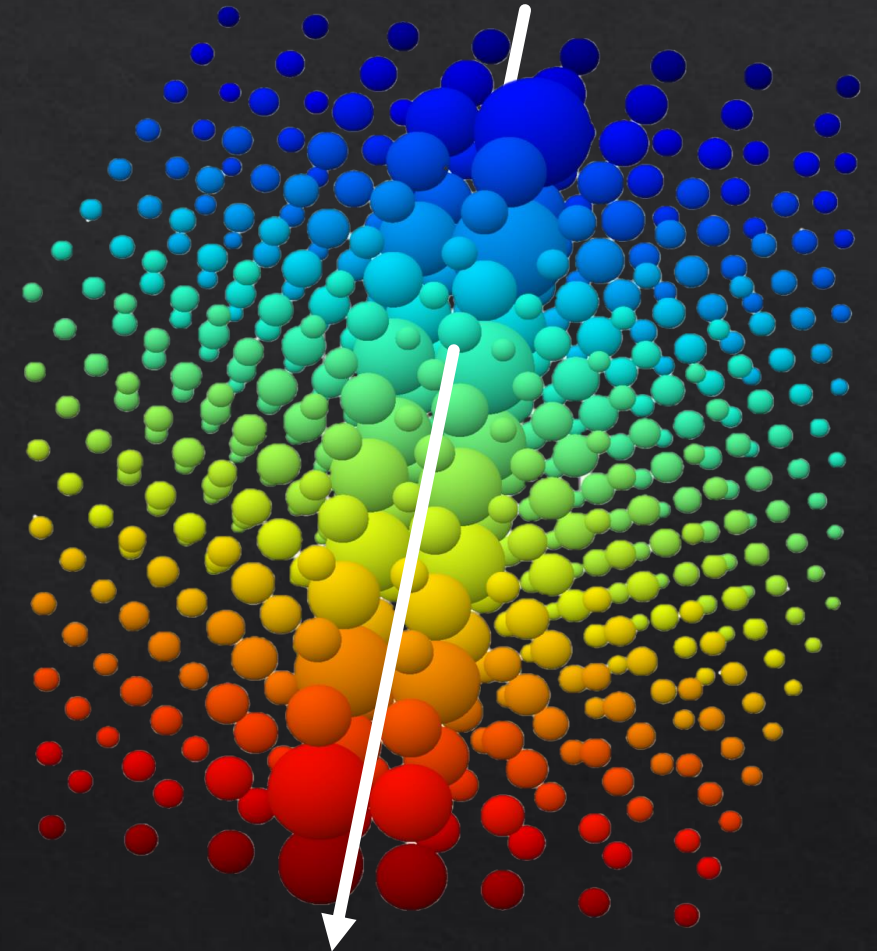
- ◇ Current Challenge: Noise
- ◇ For a Dark Matter particle detection, it is estimated that some  $10^9$  sensors *in the path* of the particle are required to have a significant Detection
- ◇ Test Statistic: Signal-to-Noise Ratio

# Physical Experiment: Protochime



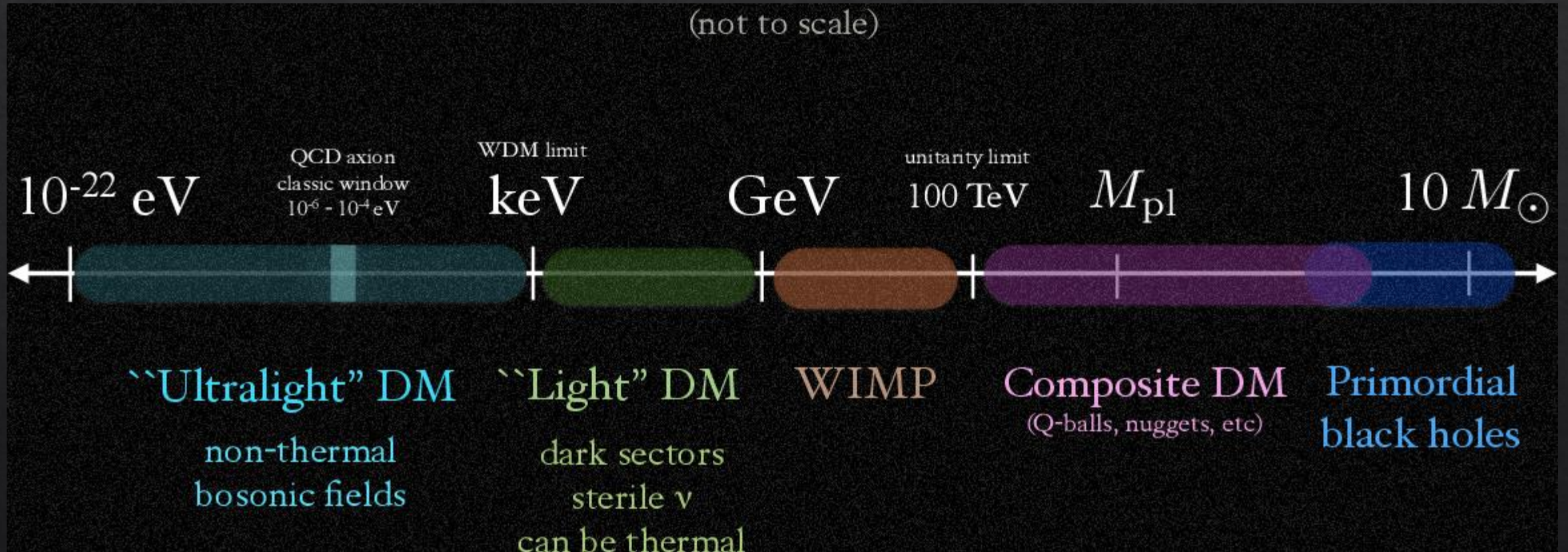
Bahaa Elshimy

# Virtual Experiment



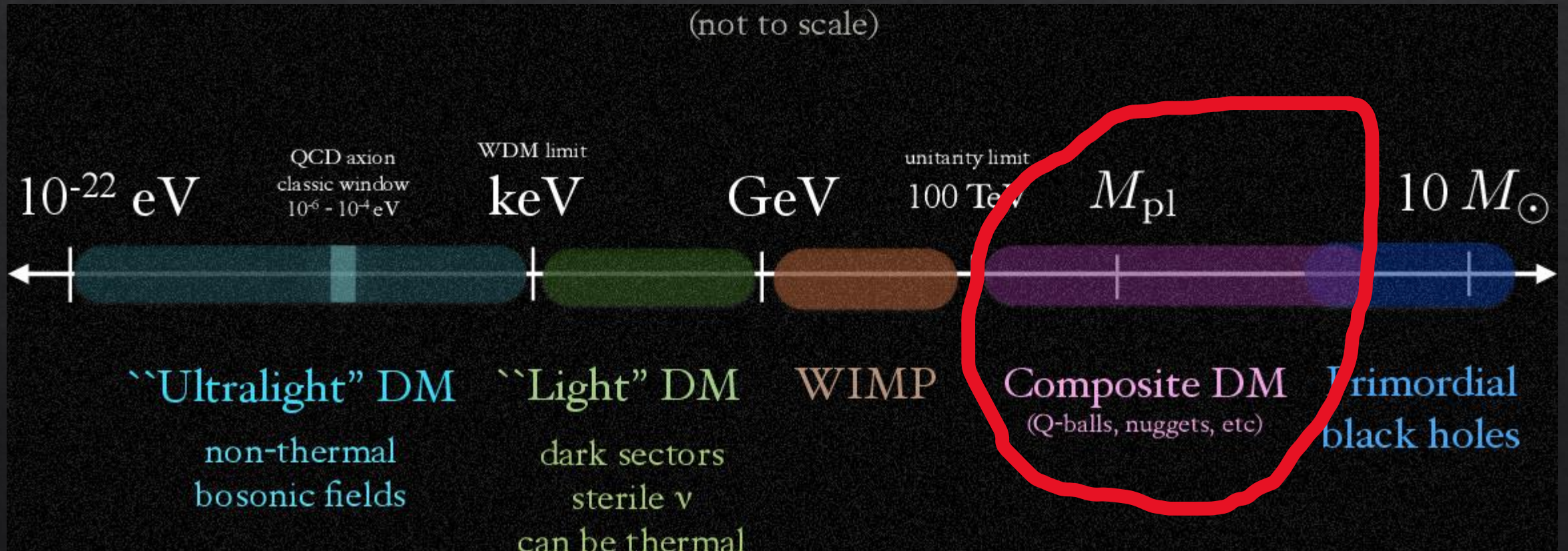
# What Kinds of Particles Do We Expect?

(not to scale)



# My Focus

(not to scale)



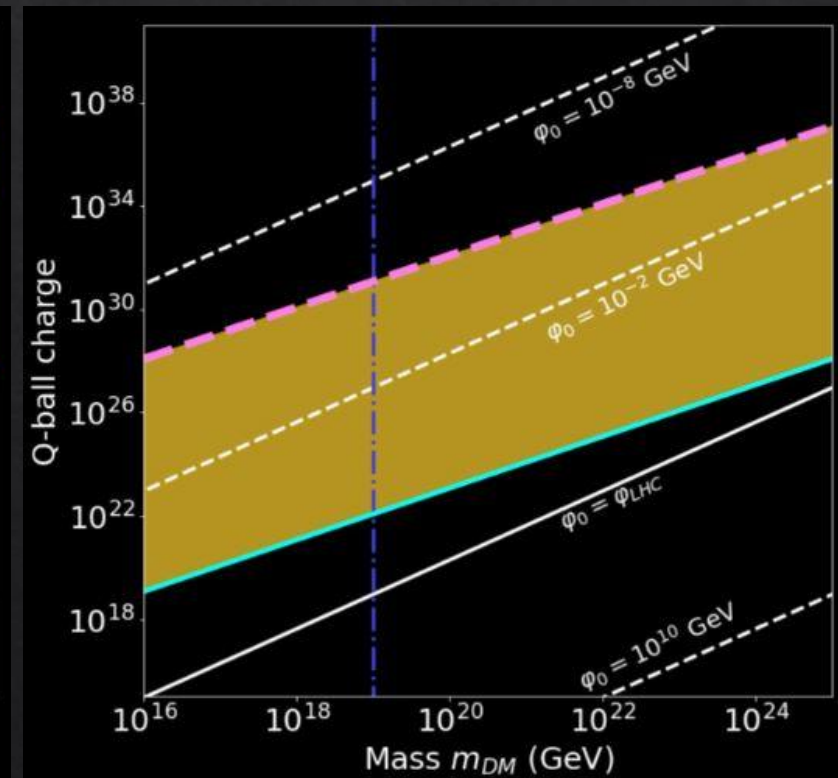
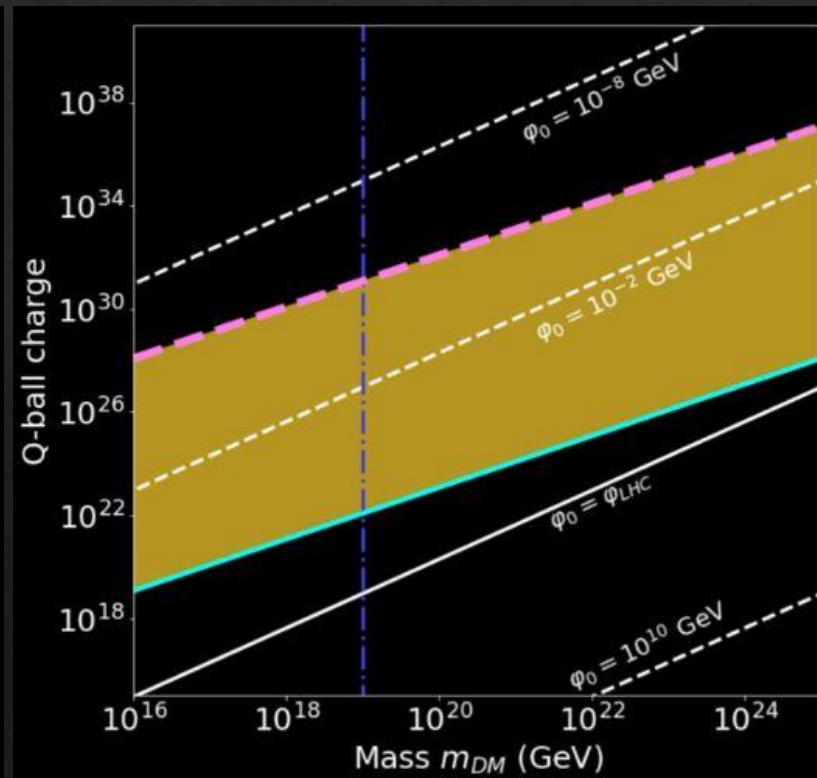
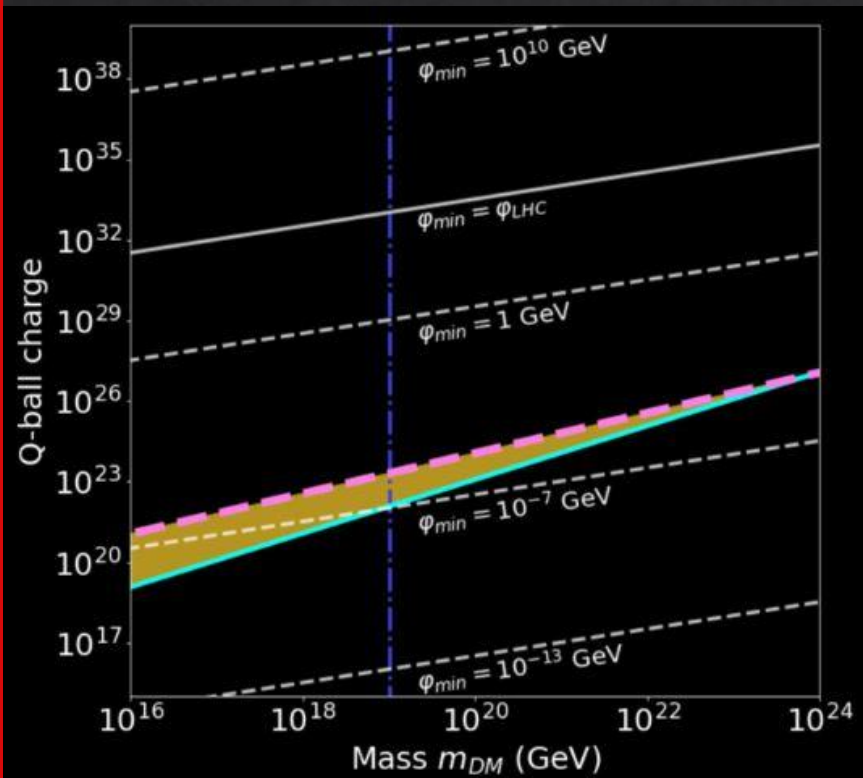
# My Focus

- ◇ Composite Dark Matter
  - ◇ DM Candidates composed of constituent particles
- ◇ Q-Balls – Non-Topological Solitons
  - ◇ Soliton solutions that admit a charge and allow for an energetically favorable massive state
- ◇ Superheavy Dark Matter Candidates
  - ◇ e.g. Extremal and “standard” PBH Relics and Gravitationally Produced particles (such as WIMPZILLAs)
- ◇ Flux Factor for a given candidate (mass) observed at a specific exposure and SNR

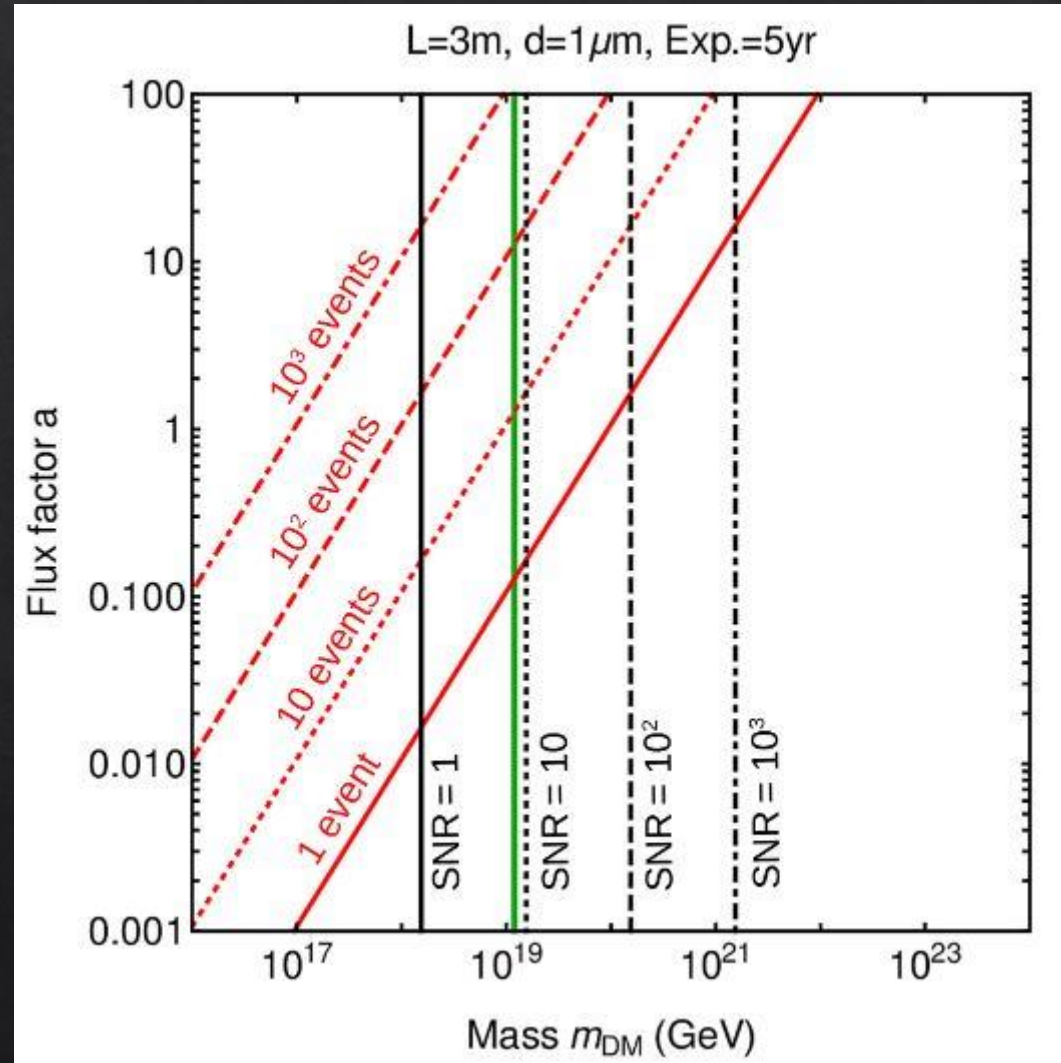


# Q-Balls

- ◇ Type I - Thin-walled: The  $\text{VeV}$  is set close to the  $\varphi_0$  of the scalar field
- ◇ Type II – Thick-walled: Gauge mediated field configuration with a flat potential
- ◇ Type III – Thick-walled: Same as Type II but with a logarithmic potential



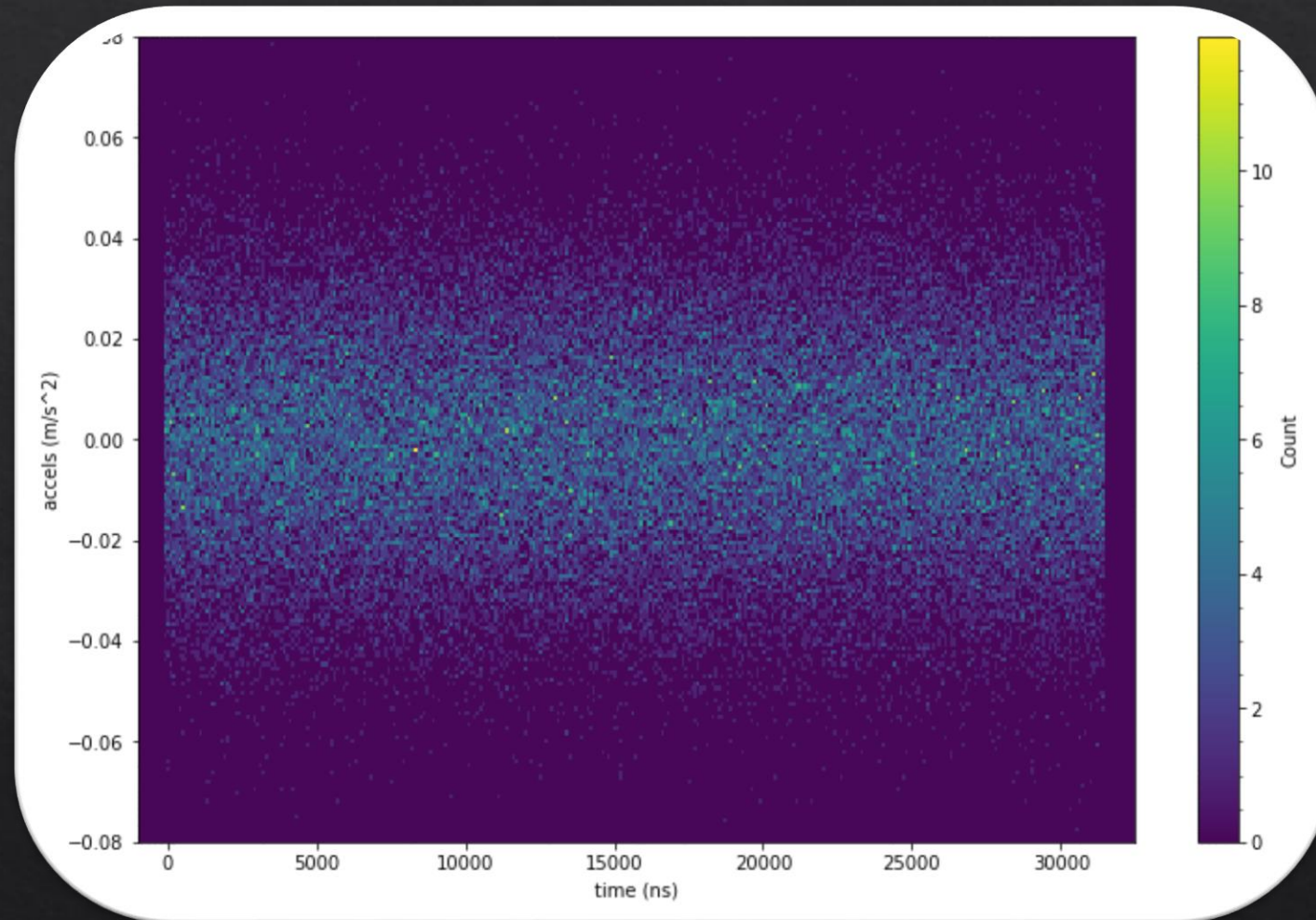
# Multicandidate Flux Factor



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# Acceleration Data

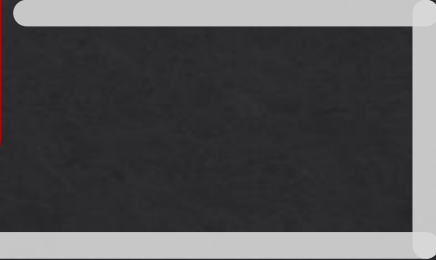


# Detector

DM Particle  
Track



Acceleration  
Data

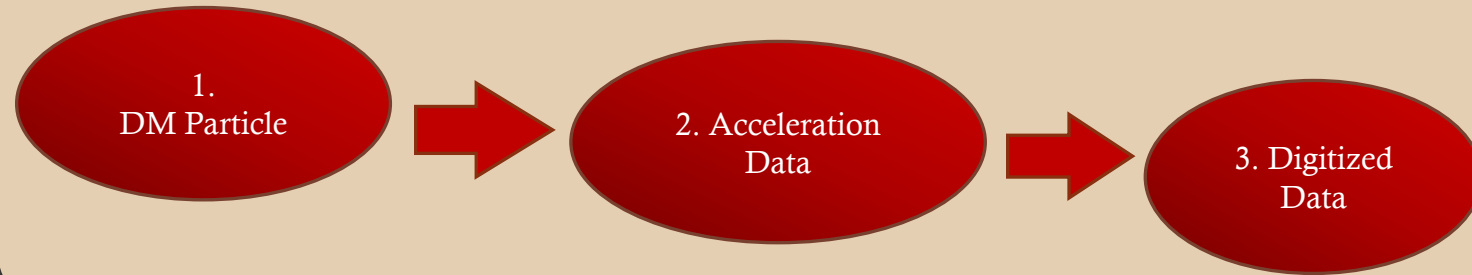


Analysis Framework

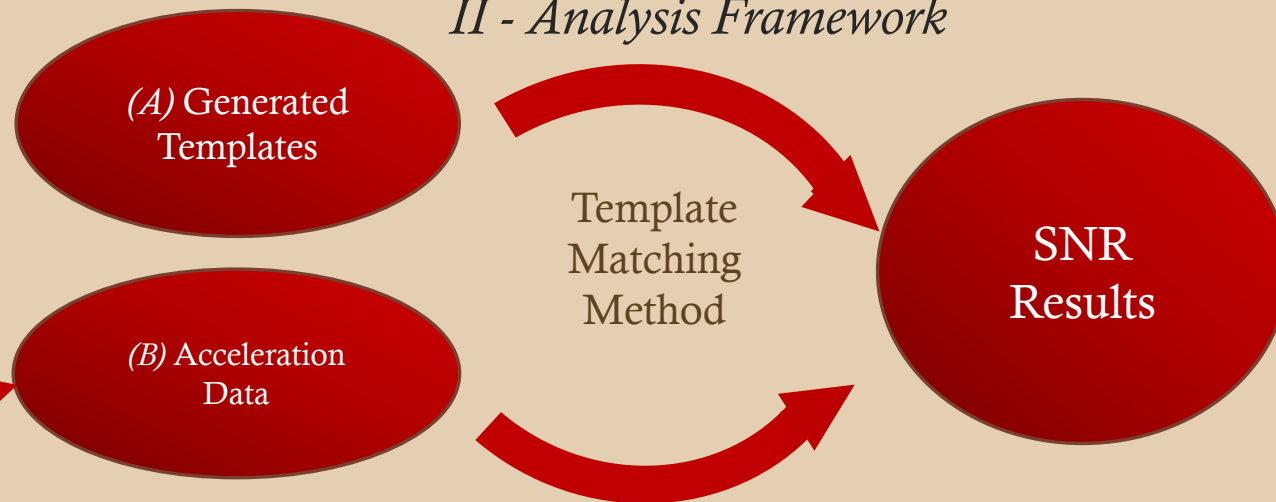


Track Identification 

## *I - Simulation Framework*



## *II - Analysis Framework*

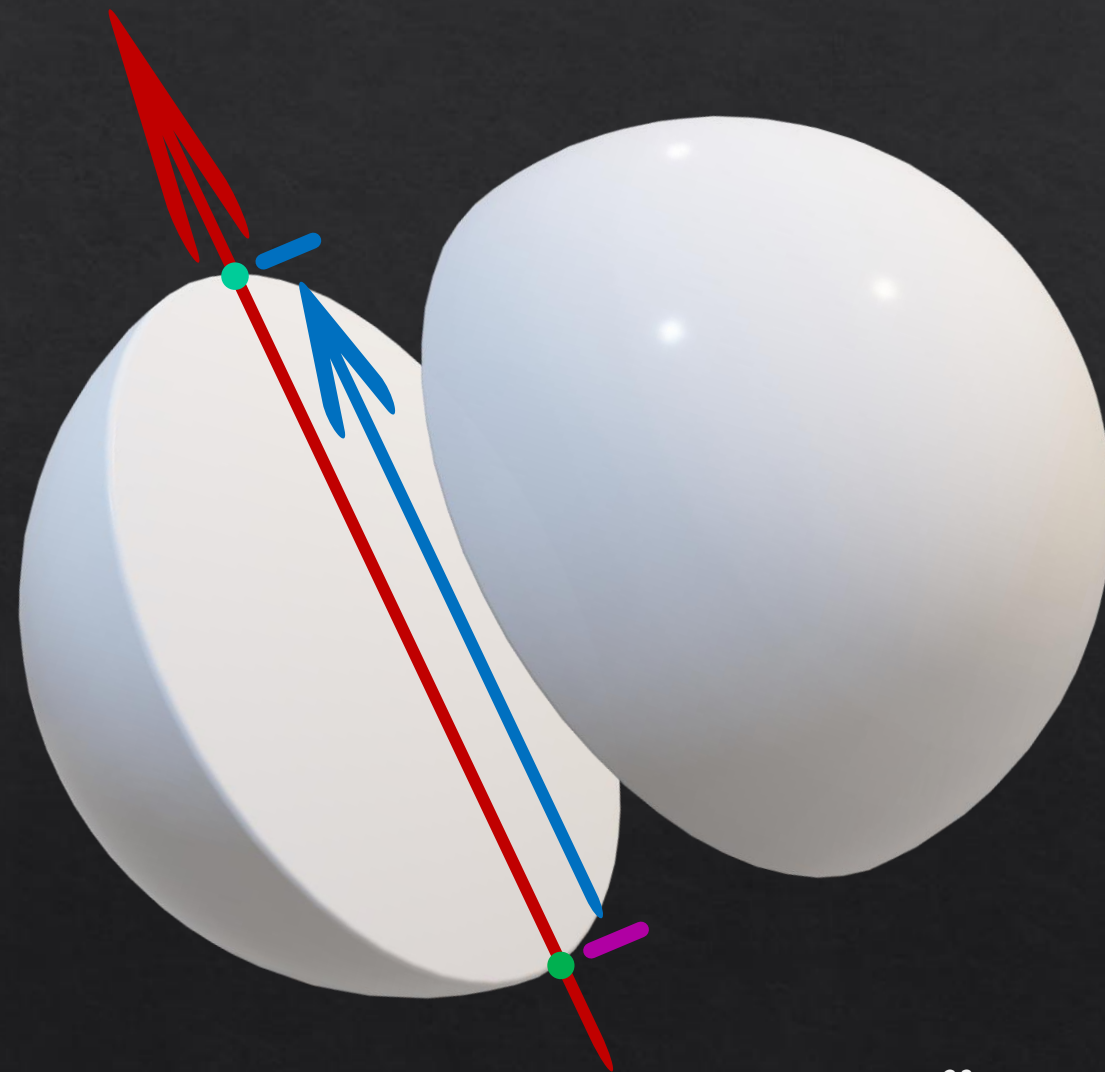


Track Identification

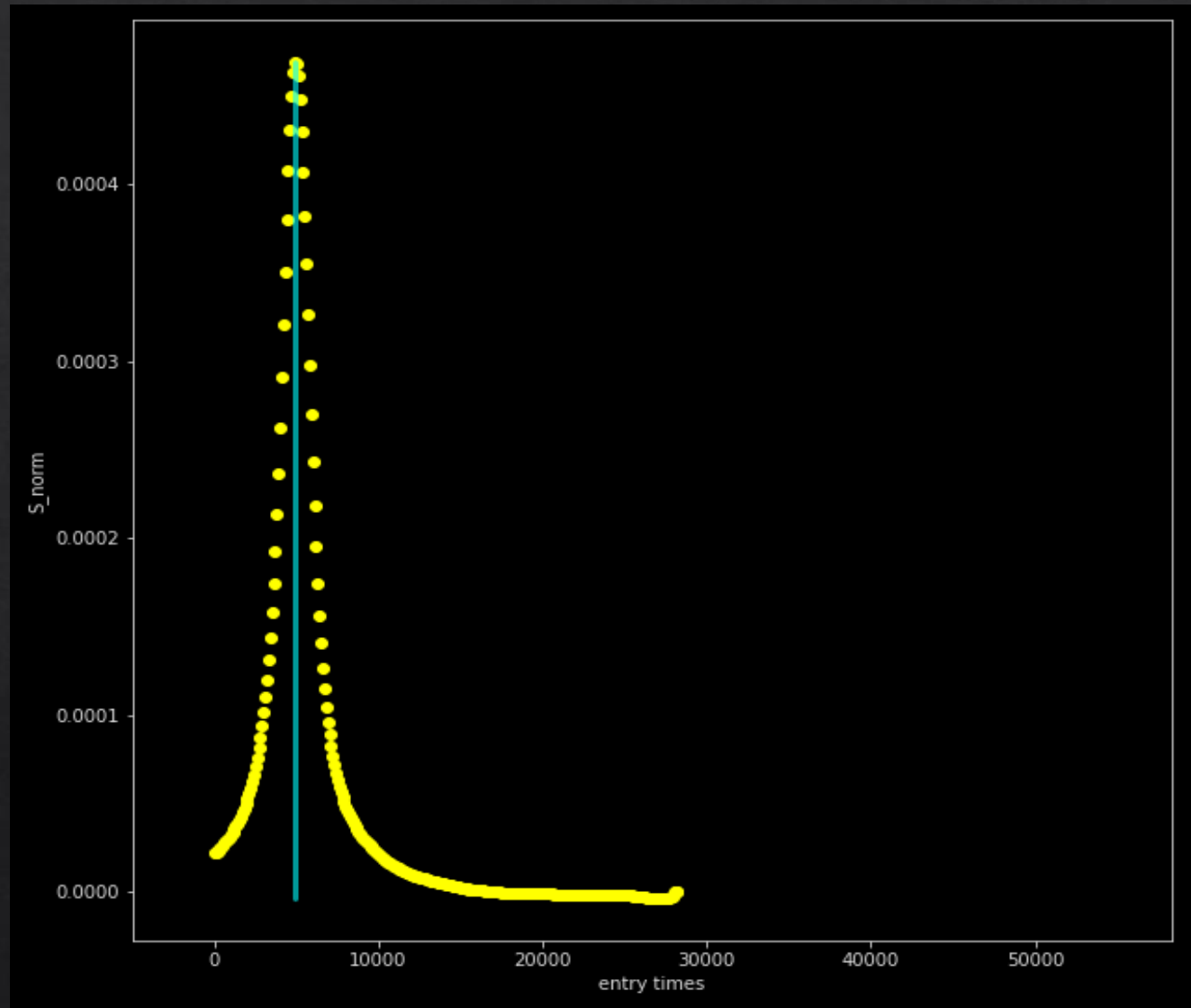


# Template Analysis Parameters

$t_{\text{entry}}$   $v_{\text{exit}}$   $\theta_0$   $\varphi_0$   $\theta_1$   $\varphi_1$

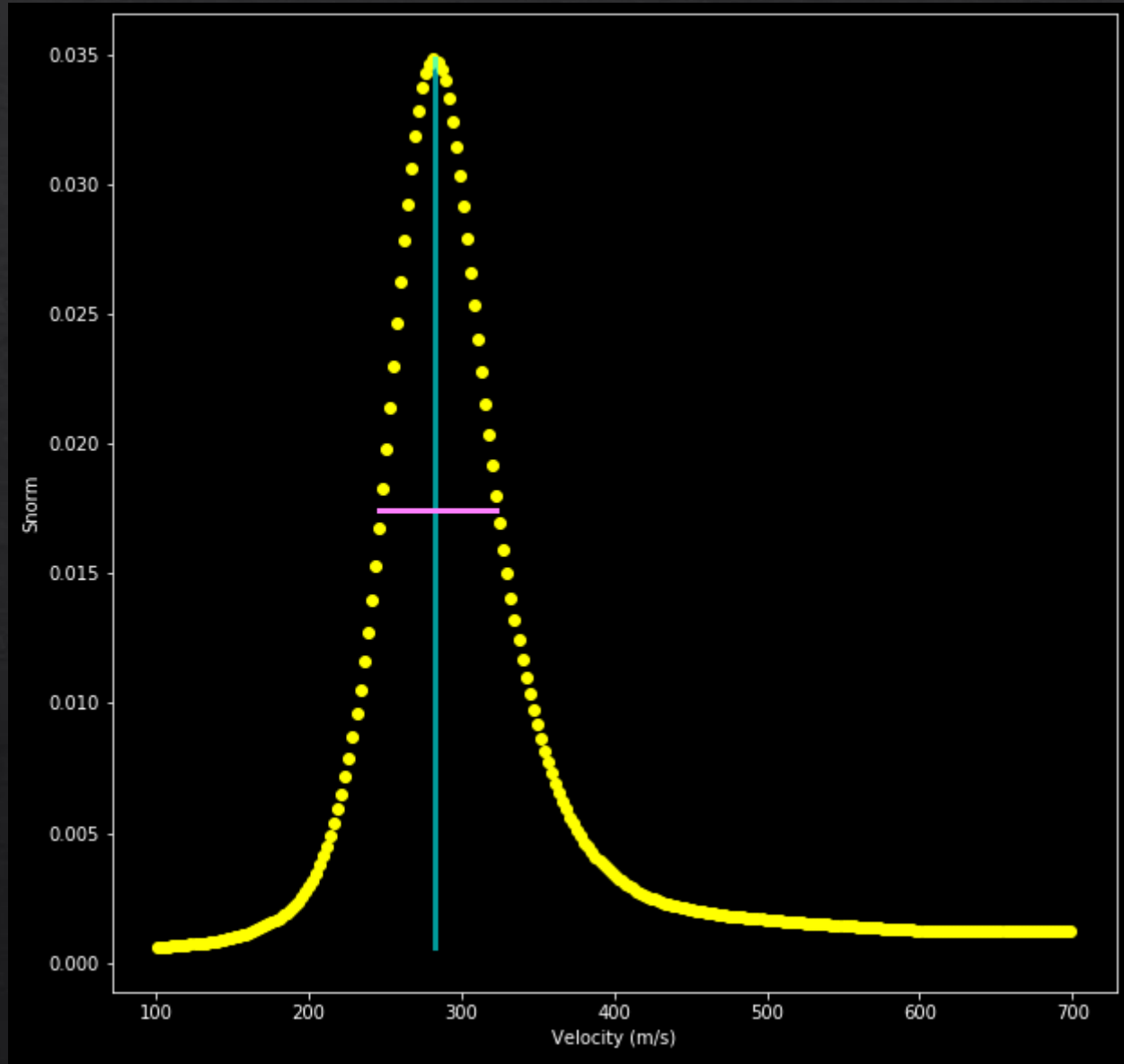


# Time Analysis

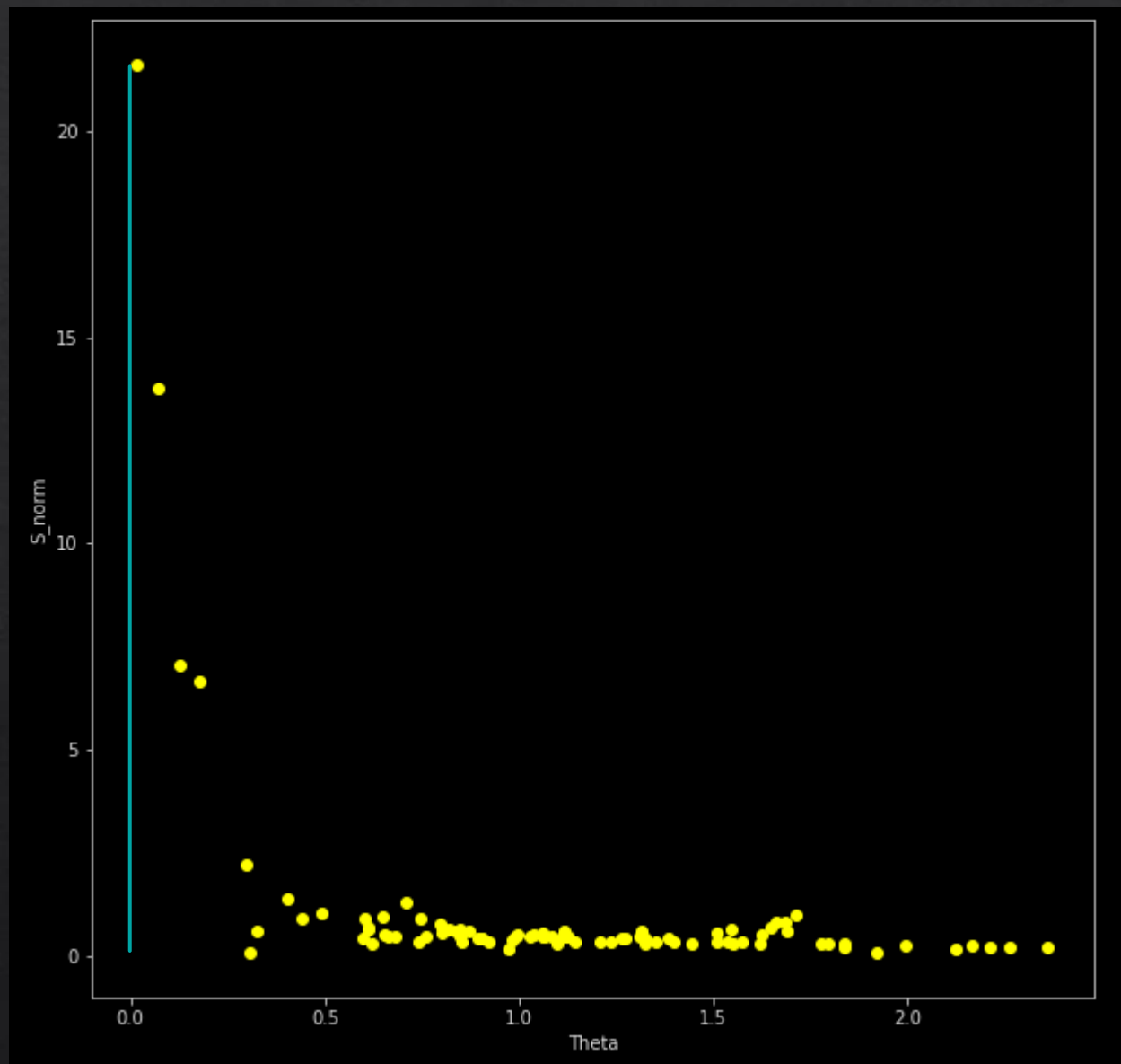




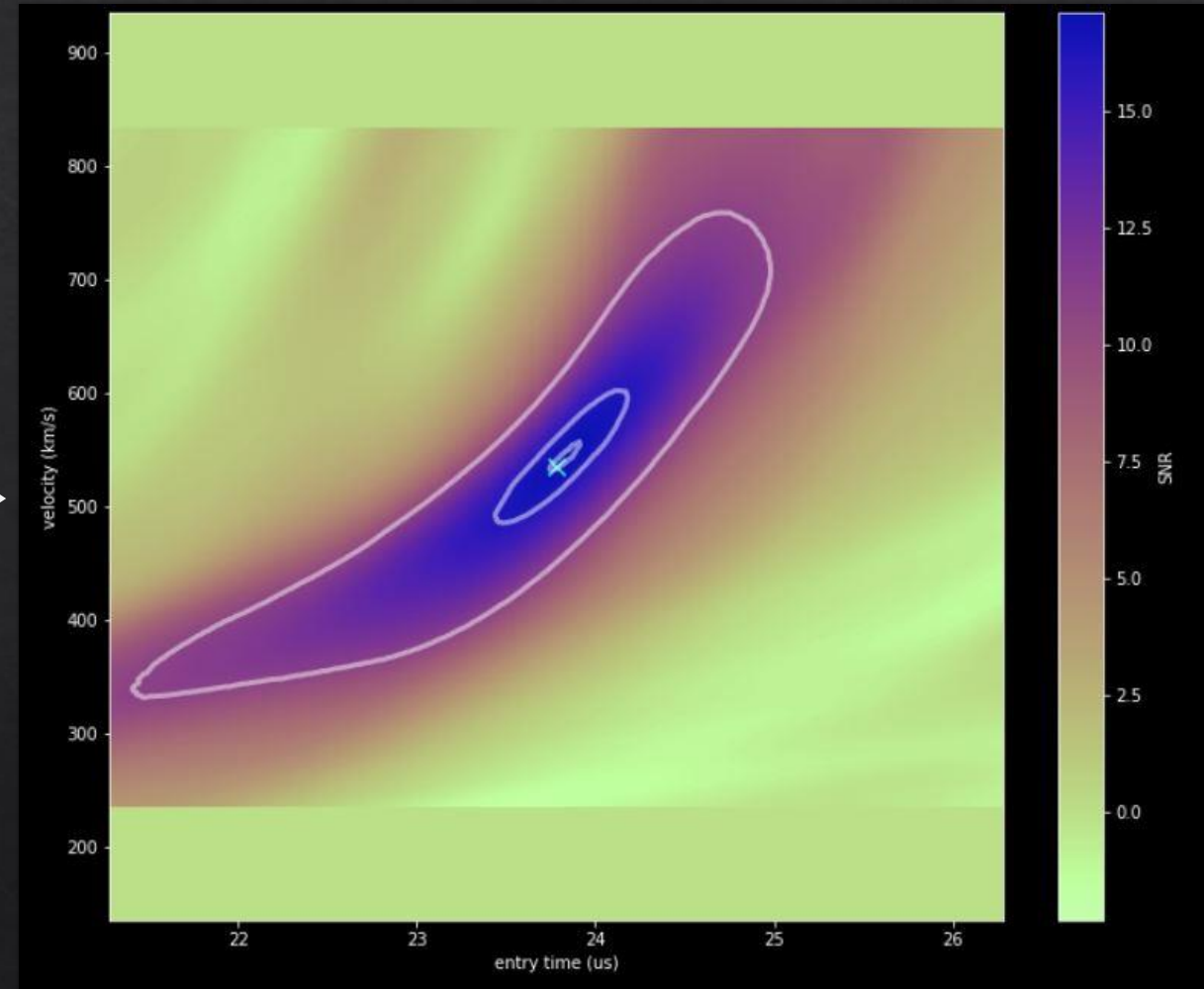
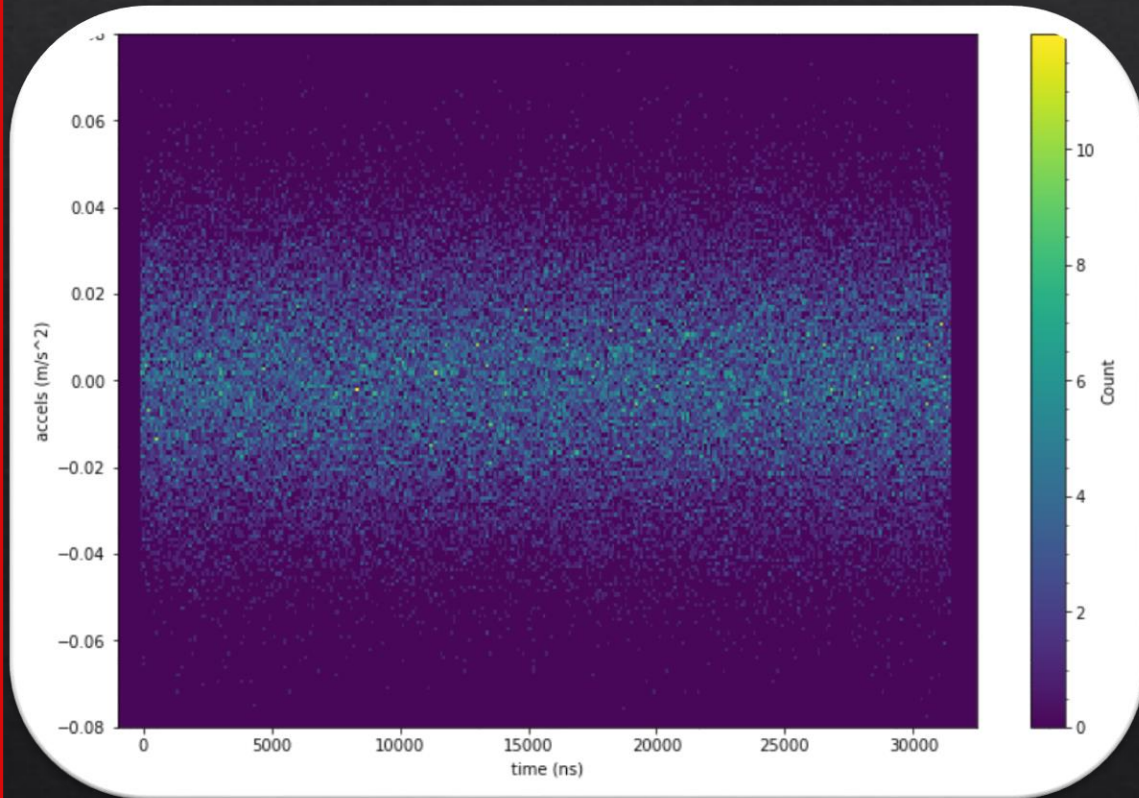
# Velocity Analysis



# Angular Analysis



# Time & Velocity Analysis

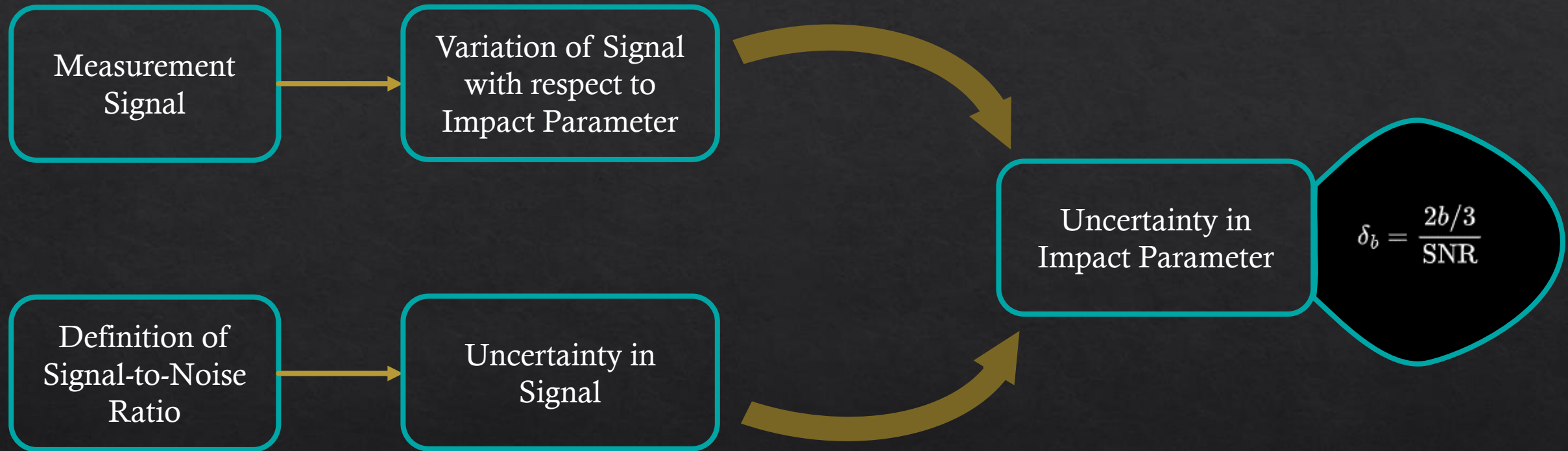


# Resolution of the Windchime Detector

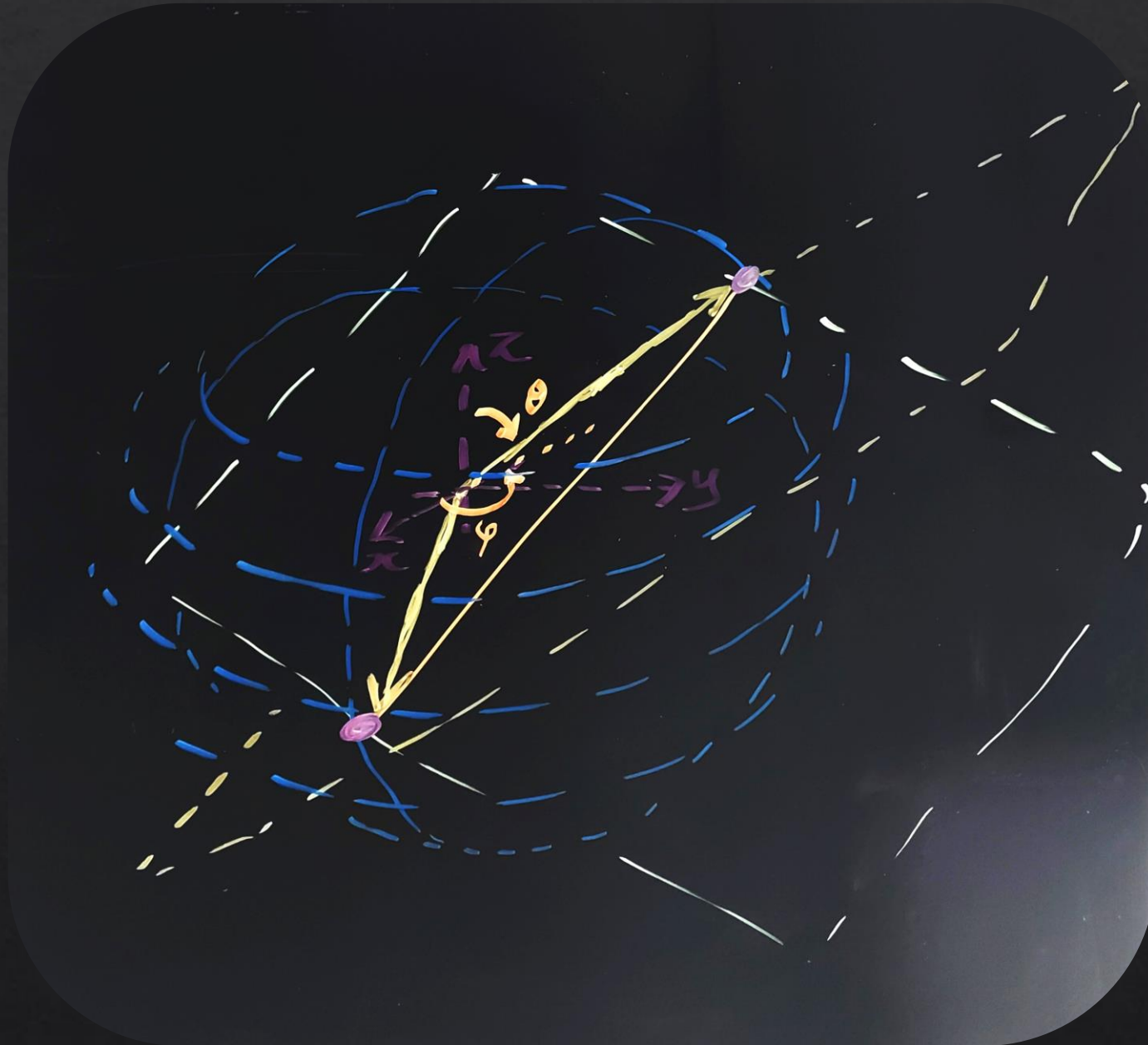
- ◇ Capacity to distinguish between different tracks in the detector
  - ◇ Smaller Resolution = Better Detector
- ◇ Defined through the uncertainty of the track parameters caused by sensor measurement errors
  - ◇ Temporal Resolution – Depends on the Exposure Time
  - ◇ Spatial Resolution – Depends on the Detector Geometry



# Sensor Uncertainty

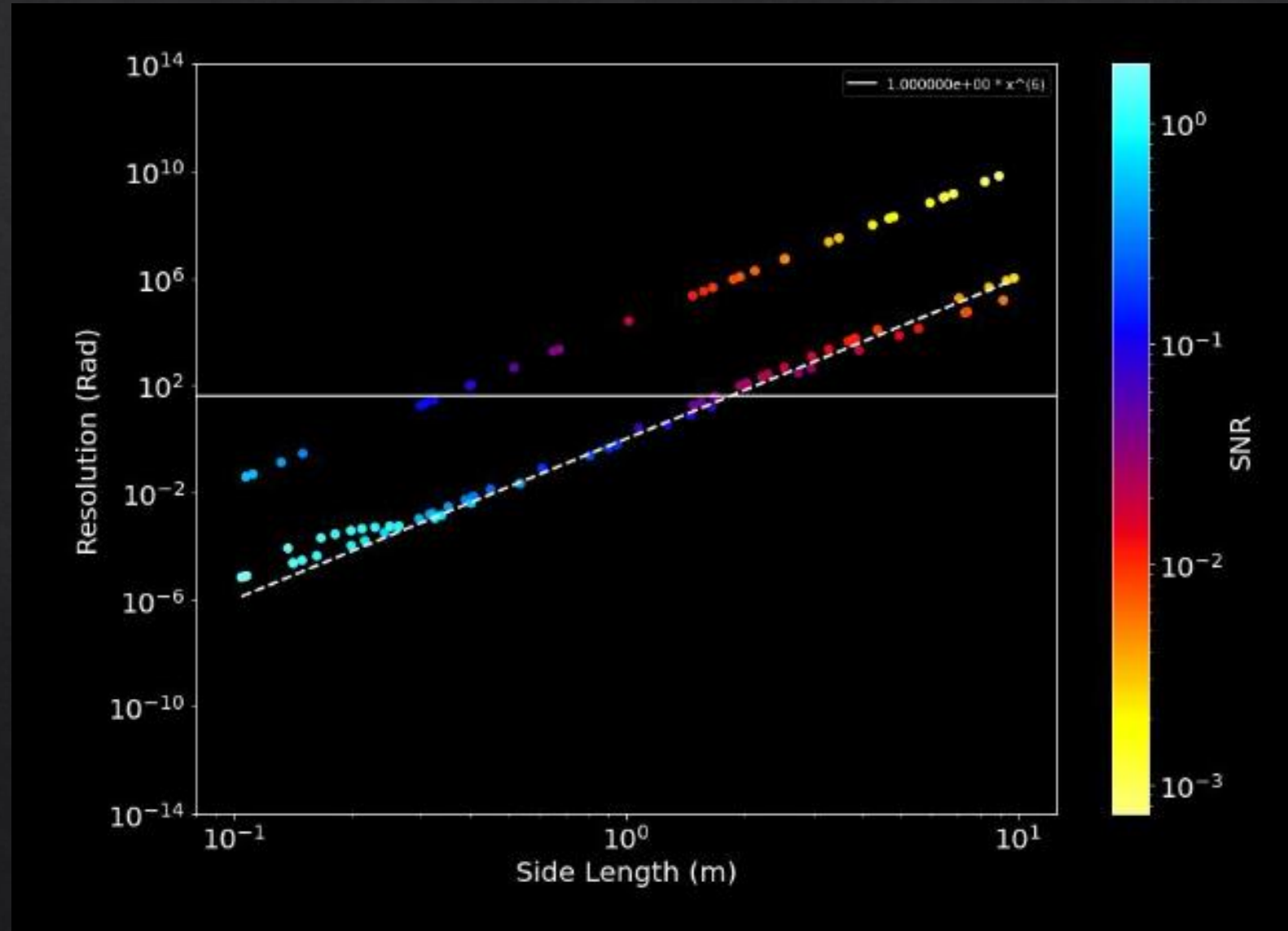


# Spatial Resolution Model in 3D



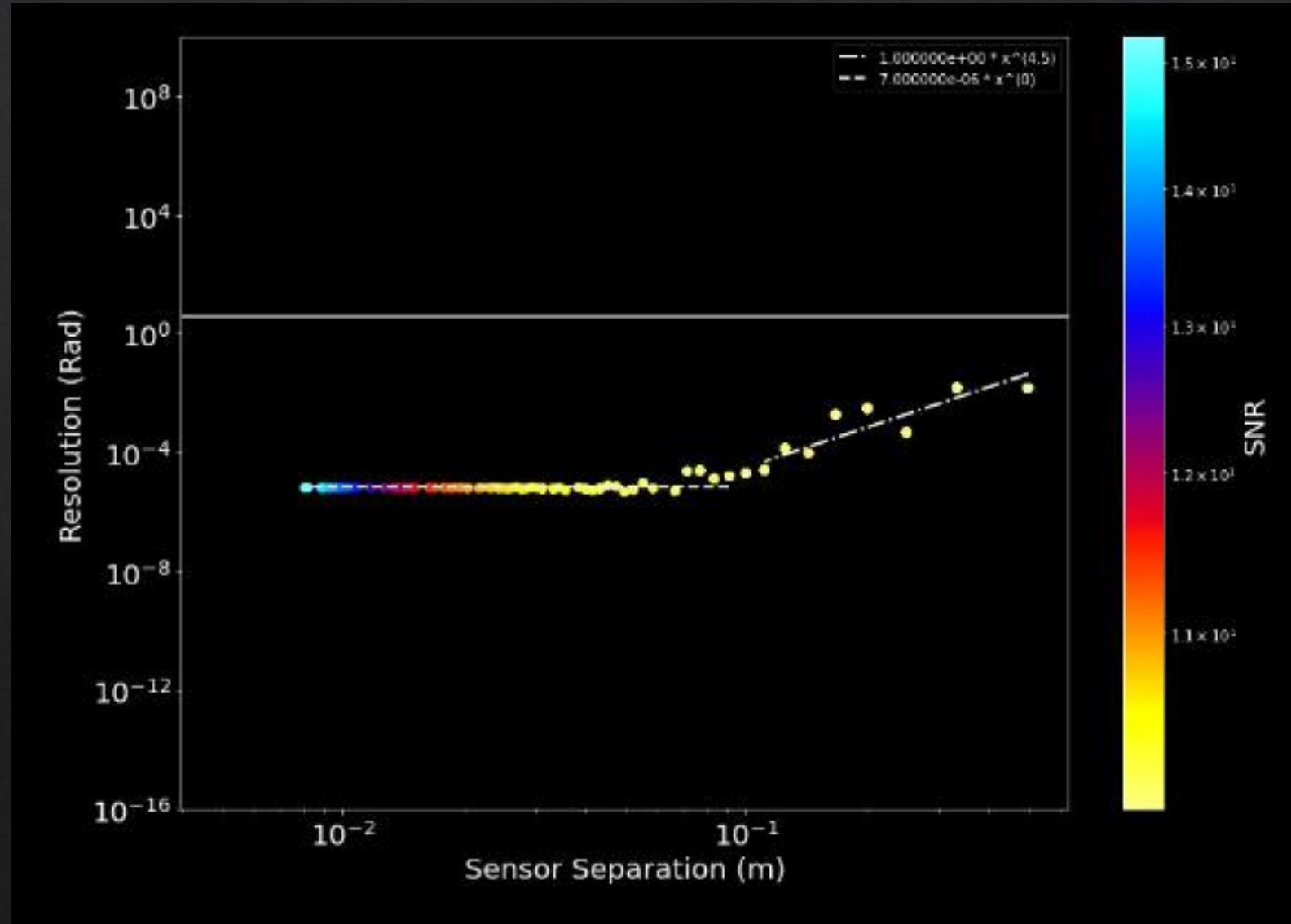
# Some of the Results

Constant Number  
of Sensors  
3D Analysis



# Some of the Results

Constant SNR and  
Constant Side Length  
2D Analysis





# Trial Factor

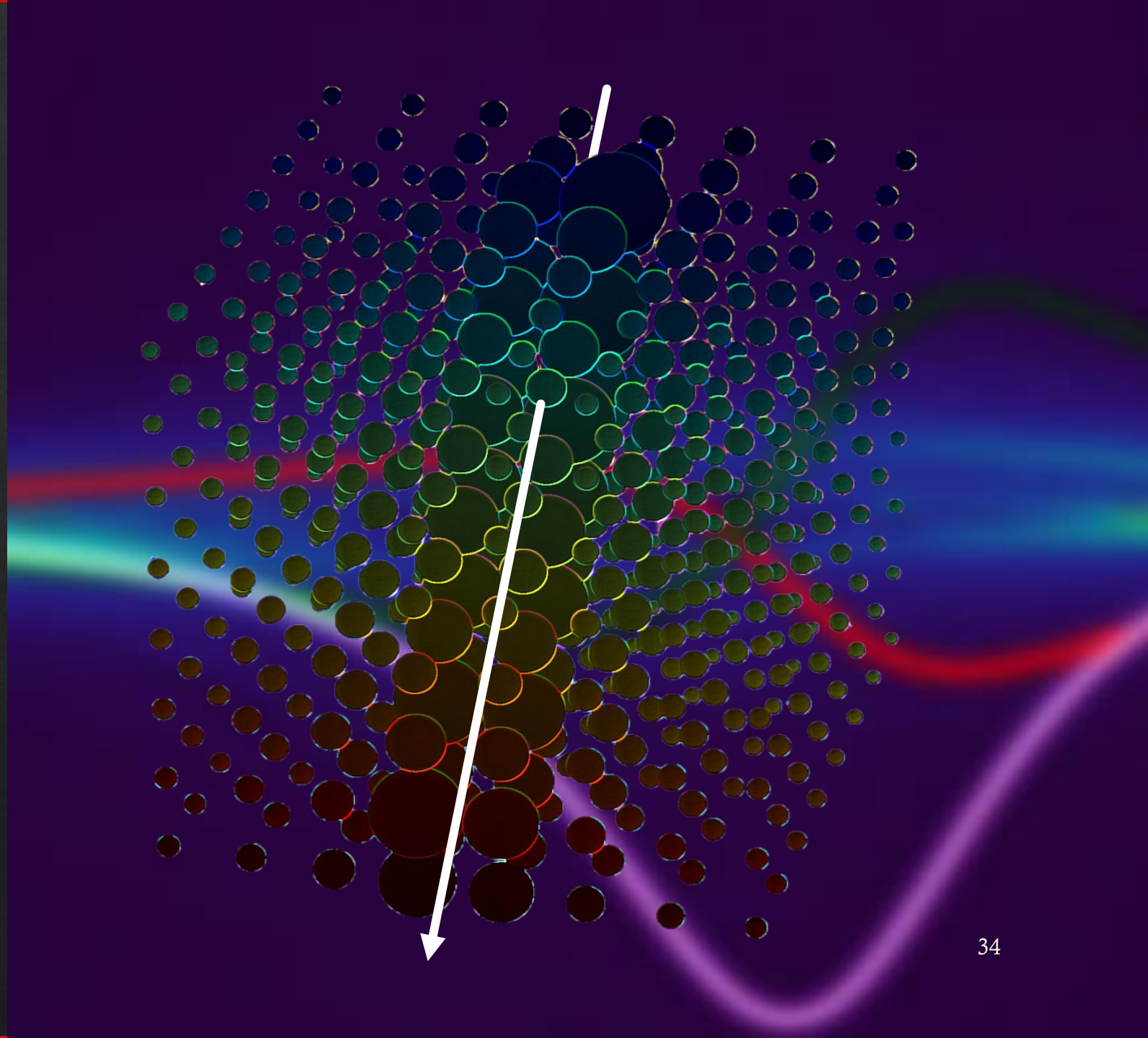
- ◇ A measure of how likely it is to have a *False Positive* detection purely given the size of the parameter space

Smaller (better) Resolution = Larger Template (parameter) Space = Larger Trial Factor

$$\text{Trial Factor} = \frac{\text{Range Vol}}{\text{Resolution Vol}} \times Z^{\#Dim-1} = \frac{4\pi^4}{\delta_{\theta,entry}\delta_{\theta,exit}\delta_{\varphi,entry}\delta_{\varphi,exit}} \times \text{SNR}^3$$

For a specific given detector setup, this takes the detection significance threshold from an *SNR of 3* to an *SNR of 10*

# The State of Dark Matter Detection is Going Gravitational!



# Thank You!

## References

- ◇ Gravitational Direct Detection of Dark Matter - <https://arxiv.org/pdf/1903.00492.pdf>
- ◇ Snowmass 2021 White Paper: The Windchime Project - <https://arxiv.org/pdf/2203.07242.pdf>
- ◇ Models of ultra-heavy dark matter visible to macroscopic mechanical sensing arrays - <https://arxiv.org/pdf/2112.14784.pdf>